

Towards a Language for Specifying Properties of Simulation Trajectories

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1 Introduction

There is an increasing interest in annotating models with information about simulation experiments. Unambiguous experiment descriptions facilitate the reproducibility of simulation results, which is a basic requirement for model publication [5]. Specifying the crucial observations from experiments regarding model behavior, together with experiment configurations (e.g., values of model parameters and stop conditions), provides useful information for model reuse [4]. The dynamic behavioral properties a model exhibits can be described by the properties of simulation trajectories produced in simulation experiments, e.g., oscillation of a protein concentration, and increase of a protein concentration to a certain peak value followed by a decrease. Often such properties and their temporal order are specified qualitatively with temporal logics like LTL (e.g., [2]). However sometimes, also quantitative temporal information about the produced trajectories is of interest.

2 Our approach

In our previous work [4], the domain specific language SESSL (Simulation Experiment Specification via a Scala Layer) was extended to specify Linear Temporal Logic (LTL) properties and simple probabilistic statements. Based on that, we now propose a language to describe properties of trajectories. The language currently allows to specify properties explicitly referring to time points (denoted with P) and episodes (denoted with E). In both cases, time constraints and an identifier (which can be used for further constraints) can optionally be added. The three parts of the pattern, i.e., properties, time constraints, and identifiers, are separated by semicolons. For example, $P((a > 0); t > 5 \wedge t < 8; t)$ states that between time point 5 and 8 a time point t exists where the model variable a is greater than 0. While describing an episode, the start, the end or the length can be specified, e.g., $E((a > 0); start = 5 \wedge len > 3;)$ states $a > 0$ holds during an anonymous episode starting from time point 5 and lasting for more than 3 units. Episodes can be related to each other using Allen's interval algebra [1], e.g., X before Y means episode X ends some time before episode Y begins. As primitive

properties we consider increasing, decreasing, peaking, stability and oscillation of a variable as well as being in a steady state. As we are aiming at stochastic models whose results may be noisy, we define these properties as trends over episodes. For example, an experiment with the Wnt model [3] with an assumed peak of the beta-catenin concentration in a parameter range can be specified (and executed) in SESSL as follows:

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1 val exp = new Experiment with Observation with Hypotheses {
2   model = "file-mlrj:./WntAxinModel.mlrj"
3   scan("kAxin_P" <~ range(0.1, 0.1, 5)) // corresponds to kA -> kAp
4   scan("kAxin_uP" <~ range(0.01, 0.01, 0.5)) // corresponds to kAp -> kA
5   stopTime = 720
6   observe("Cell/Nuc/Bcat()") // beta-catenin is observed
7   observeAt(range(1, 10, 720))
8   // peak between time point 50 and 150 with a value between 0.1 and 2.4
9   assume(Pr(P(Peak("Cell/Nuc/Bcat()") = v; t ≤ 50 ∧ t ≥ 150; t) ∧
10     v > 0.1 ∧ v < 2.4) >= 0.8)
11 }

```

Another key feature of the language is a measurement of similarity to other experiment results (e.g., wet-lab data): given a set of timed data points with error bars, a distance metric and an error threshold, it determines whether a trajectory is sufficiently similar to the given data points. With further discussion needed referring to the language’s expressiveness and complexity, the proposed constructs are currently tested in cell biological applications.

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